Projective metrics and contraction principles for complex cones

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November 18, 2008

Abstract

In this article, we consider linearly convex complex cones in complex Banach spaces and we define a new projective metric on these cones. Compared to the hyperbolic gauge of Rugh, it has the advantage of being explicit, and easier to estimate. We prove that this metric also satisfies a contraction principle like Birkhoff's theorem for the Hilbert metric. We are thus able to improve existing results on spectral gaps for complex matrices. Finally, we compare the contraction principles for the hyperbolic gauge and our metric on particular cones, including complexification of Birkhoff cones. It appears that the contraction principles for our metric and the hyperbolic gauge occur simultaneously on these cones. However, we get better contraction rates with our metric.

AMS Subject classification codes (2000): 15A48, 47A75, 47B65.

1 Introduction

In his article [Bir57] (see also [Bir67]), Birkhoff proved that the Hilbert projective metric on convex cones satisfies a contraction principle. He showed that a linear map T preserving a cone is a contraction for the Hilbert metric; and that this contraction is strict and uniform when the image of the cone is of finite diameter. He used this idea to prove various theorems on positive operators. This technique of projective metrics permits to avoid the use of the Leray-Schauder fixpoint theorem as in [Kr48]. It is typically useful when the operator one considers is not compact, and was extensively used in thermodynamic formalism (see for instance [FS79], [FS88] and [Liv95]).

Recently (see [Rugh07]), Rugh extended the contraction principle of Birkhoff to complex cones in complex Banach spaces. He introduced a new projective gauge d_C on

complex cones and gave a very general contraction principle. He then proved various extensions of existing results on positive operators to a complex setting. Also, he had to abandon the convexity assumption on the cone which is a very useful condition in the real case. As a consequence, the complex gauge does not satisfy the triangular inequality in general, and there is not anymore a notion of dual cone.

As a substitute for convexity, there is the natural notion of linear convexity in the complex setup. The dual complement of a linearly convex complex cone then replaces the real dual cone. These notions originally come from several complex variables analysis and were introduced for open sets in \mathbb{C}^n by Martineau in [Mar66] (see also [An04] for more on the subject and historical notes). A complex cone is said to be linearly convex if through each point in its complement, there passes a complex hyperplane not intersecting the cone; and then, the dual complement is the set of all linear functionals not vanishing on the cone. The central idea of our paper is to use this notion of duality to study complex cones.

In the present paper, we define first (in section 2) a new projective gauge δ_C analogously to the Hilbert metric (compare with formulas (2.5) and (2.6) for the Hilbert metric). Let C be a complex cone in a complex Banach space and let x and y be independent vectors in C. Then $\delta_C(x,y)$ is defined to be $\log(b/a)$, where b and a are respectively the supremum and the infimum of the modulus of

$$E_C(x,y) = \{ z \in \mathbb{C} : zx - y \notin C \}. \tag{1.1}$$

 δ_C is actually a projective metric (meaning that it satisfies the triangular inequality) for a large family of cones, including for instance linearly convex cones and the cones of section 4. For general complex cones, we prove also that δ_C satisfies a contraction principle similar to Birkhoff's theorem.

We study more precisely the case of complex matrices in section 3. First of all, recall that a real matrix A satisfies $A(\mathbb{R}^n_+ \setminus \{0\}) \subset \operatorname{Int} \mathbb{R}^n_+$ if and only if all its entries are positive. Besides, the Perron-Frobenius theorem claims that in such a situation, the matrix A has a spectral gap. In other words, there exists a unique eigenvalue λ_m of maximal modulus, which is simple, and the others are of modulus not greater than $c|\lambda_m|$, c<1. Moreover, a positive matrix A contracts strictly and uniformly the Hilbert metric of \mathbb{R}^n_+ . This gives an estimate of the 'size' c of the spectral gap: one may take the contraction coefficient of the Hilbert metric $c = \tanh(\Delta/4) < 1$ given by Birkhoff's theorem. Here $\Delta = \sup_{x,y \in \mathbb{R}^n_+ \setminus \{0\}} h_{\mathbb{R}^n_+}(Ax,Ay) < \infty$ is the diameter of $A(\mathbb{R}^n_+ \setminus \{0\})$ with respect to the Hilbert metric $h_{\mathbb{R}^n_+}$.

This result is generalized in [Rugh07]: a natural extension $\mathbb{C}^n_+ \subset \mathbb{C}^n$ of \mathbb{R}^n_+ is defined; and it is proved (among other things) that a complex matrix A such that

$$A(\mathbb{C}^n_+ \setminus \{0\}) \subset \text{Int } \mathbb{C}^n_+ \tag{1.2}$$

has a spectral gap. Using some kind of perturbation argument, Rugh proves also that the complex matrices $A = (a_{ij})$ such that $|\Im(a_{ij}\overline{a_{kl}})| < \alpha \le \Re(a_{ij}\overline{a_{kl}})$ for all indices are examples of matrices satisfying (1.2). This perturbation technique gives good estimates of the size of the spectral gap only when the matrix A is close to a positive matrix.

Here, we study the complex cone of all complex matrices satisfying (1.2). We give a simple condition on the coefficients a_{ij} that characterizes these matrices, and we

provide a sharp estimate of the size of their spectral gap. We summerize our results on complex matrices in the following theorem.

Theorem 1.1. The complex matrices A satisfying $A(\mathbb{C}^n_+ \setminus \{0\}) \subset \operatorname{Int} \mathbb{C}^n_+$ are exactly the matrices satisfying for all indices

$$\Re(\overline{a_{kp}}a_{lq} + \overline{a_{kq}}a_{lp}) > |a_{kp}a_{lq} - a_{kq}a_{lp}|.$$

These matrices have a spectral gap. If λ_m is the leading eigenvalue, the other eigenvalues are of modulus not greater than $c|\lambda_m|$. The size c of the spectral gap is given by $c = \tanh(\Delta/4) < 1$, where Δ is the diameter of $A(\mathbb{C}^n_+ \setminus \{0\})$ with respect to our projective metric $\delta_{\mathbb{C}^n_+}$. We get also the following simple estimate for Δ . If $\theta \in (0,1)$ and $\sigma > 1$ are such that

$$\Re(\overline{a_{kp}}a_{lq} + \overline{a_{kq}}a_{lp}) > \frac{1}{\theta}|a_{kp}a_{lq} - a_{kq}a_{lp}|,$$
$$|a_{kp}a_{lq}| \leq \sigma^{2}|a_{kq}a_{lp}|.$$

then

$$\delta$$
-diam $A(\mathbb{C}^n_+ \setminus \{0\}) \le 8 \log \frac{1+\theta}{1-\theta} + 2 \log \sigma$.

Finally, in section 5 we compare the complex gauge d_C , and the metric δ_C . Recall the definition of the gauge d_C . Let C be a complex cone and $x, y \in C$ linearly independent. If 0 and ∞ belong to the same connected component U of the interior $\mathring{L}(x,y)$ of

$$L(x,y) = \{ z \in \hat{\mathbb{C}} : zx - y \in C \} \subset \hat{\mathbb{C}}, \tag{1.3}$$

then $d_C(x,y)$ is the Poincaré distance in U between 0 and ∞ . Otherwise, $d_C(x,y) = \infty$, and $d_C(x,\alpha x)$ is defined to be 0. Note that $\delta_C(x,y) < \infty$ only requires that 0, $\infty \in \mathring{L}(x,y)$ but not necessarily in the same connected component of $\mathring{L}(x,y)$. This fact makes the metric δ_C easier to estimate: one does not need to study the full geometry of the set $E_C(x,y)$ as we do in section 5 but only to estimate $\sup |E_C(x,y)|$ and $\inf |E_C(x,y)|$. The use of δ_C also avoids some technical complications in proofs, see Example 1.

To make comparison between d_C and δ_C possible, we restrict ourselves to the complex cones of section 4 (including canonical complexifications of real Birkhoff cones defined in [Rugh07] and thus \mathbb{C}^n_+). On these cones, the geometric configuration of the sets $\mathring{L}(x,y)$ is quite simple: it is simply connected, and its complement is a union of disks and half-planes (a finite union in the case of \mathbb{C}^n_+). We are thus able to prove the following inequalities.

$$\frac{1}{2}\delta_C(x,y) \leq d_C(x,y),$$

$$d_C(x,y) \leq \pi\sqrt{2}\exp(\delta_C(x,y)/2),$$

$$d_C(x,y) \leq 3\delta_C(x,y) \text{ if } \delta_C(x,y) < \delta_0.$$
(1.4)

Here, $\delta_0 > 0$ does not depend on the cone. Though the constants are probably not optimal, the exp is necessary in (1.4). So the δ_C -diameter is in general significantly

smaller than the d_C -diameter and thus gives a better estimate of spectral gaps size (see Remark 6). However, this proves also that the condition of being of finite diameter does not depend on whether we use δ_C or d_C . This means that the contraction principle in [Rugh07] and the one we prove for δ_C occurs simultaneously for our family of cones.

The gauge d_C does not satisfy the triangular inequality (even on \mathbb{C}^n_+ , $n \geq 3$, see Remark 6). So we study the projective metric (introduced in [Rugh07]) associated to d_C , namely $\tilde{d}_C(x,y) = \inf \sum d_C(x_i,x_{i+1})$. The preceding inequalities show that on our family of cones, \tilde{d}_C is nondegenerate, and controls d_C . So, being of finite diameter for \tilde{d}_C implies being of finite diameter for d_C . Therefore, \tilde{d}_C also obey a contraction principle. Even though \tilde{d}_C satisfies the triangular inequality and also a contraction principle, it should be noted that it is more difficult to estimate \tilde{d}_C than d_C (and so, more difficult than δ_C).

Acknowledgments: The author expresses his deep thanks to H.-H. Rugh for his constant support and for stimulating discussions during the preparation of this work.

2 A contraction principle

If $V_{\mathbb{R}}$ is a real Banach space, and $C_{\mathbb{R}} \subset V_{\mathbb{R}}$ a proper closed convex cone, the Hilbert metric $h_{C_{\mathbb{R}}}$ of the cone $C_{\mathbb{R}}$ may be defined for $x, y \in C_{\mathbb{R}} \setminus \{0\}$ by (see [Bir57] and [Bir67])

$$h_{C_{\mathbb{R}}}(x,y) = \log \frac{b}{a},$$
 $b = \inf\{t > 0 : tx - y \in C_{\mathbb{R}}\},$ $a = \sup\{t > 0 : tx - y \in (-C_{\mathbb{R}})\}.$ (2.5)

On the other hand, the convexity of $C_{\mathbb{R}}$ permits to define a dual cone, and the Hilbert metric can be recovered from

$$h_{C_{\mathbb{R}}}(x,y) = \sup \left\{ \log \frac{\langle f, y \rangle \langle g, x \rangle}{\langle f, x \rangle \langle g, y \rangle} \right\},$$
 (2.6)

where the supremum is taken over all $f, g \in V_{\mathbb{R}}'$, nonnegative on $C_{\mathbb{R}}$ and such that $\langle f, x \rangle, \langle g, y \rangle > 0$.

Let V be a complex Banach space, V' its dual and $\langle \cdot, \cdot \rangle$ the canonical duality $V' \times V \to \mathbb{C}$.

Definition 1. Let $C \subset V$ be a non-empty subset. C is said to be

- a complex cone if $\mathbb{C}^*C \subset C$.
- proper if the closure \overline{C} of C contains no complex planes.

Note that we make no topological assumption on the cone here. When the cone C is closed, this definition of properness is the one given in [Rugh07].

Definition 2. Let C be a proper complex cone. Let $x, y \in C \setminus \{0\}$. We consider the set E(x,y) defined by

$$E(x,y) = E_C(x,y) = \{ z \in \mathbb{C} : zx - y \notin C \}.$$

We then define:

- $\delta_C(x,y) = 0$ if x and y are colinear.
- $\delta_C(x,y) = \log \frac{b}{a} \in [0,\infty]$ if x and y are linearly independent, where

$$b = \sup |E(x,y)| \in (0,\infty]$$
 and $a = \inf |E(x,y)| \in [0,\infty).$

Note that by properness of C, $E(x,y) \neq \emptyset$, and that we always have $0 \notin E_C(x,y)$.

We always have $\delta_C(x,y) = \delta_C(y,x)$, and $\delta_C(x,\lambda y) = \delta_C(x,y)$, $\lambda \in \mathbb{C}^*$. If $\delta_C(x,y) = 0$ then x and y must be colinear. Indeed, suppose they are independent. The set $E_C(x,y)$ is included in a circle C(0,M). So the vector plane spanned by x and y is included in the closure of C, and this is impossible since we assume the cone proper. However, δ_C need not satisfy the triangular inequality on a general complex cone.

Definition 3. Following [An04] (see also [Hor94]), we say that a complex cone $C \subset V$ is *linearly convex* if through each point in the complement of C, there passes a complex hyperplane not intersecting C. If a complex cone C is linearly convex, one defines its dual complement to be the set

$$C' = \{ f \in V' : \forall x \in C, \langle f, x \rangle \neq 0 \}. \tag{2.7}$$

Note that if C is linearly convex and $C \neq V$, then $0 \notin C$, $0 \notin C'$. We have also the following characterization. For all $x \in V$,

$$x \in C \iff \forall f \in C', \langle f, x \rangle \neq 0.$$
 (2.8)

Lemma 2.1. Let C a linearly convex proper complex cone, then δ_C is a projective metric on C, and we have the formula

$$\delta_C(x,y) = \sup_{f,g \in C'} \log \left| \frac{\langle f, y \rangle \langle g, x \rangle}{\langle f, x \rangle \langle g, y \rangle} \right|. \tag{2.9}$$

Proof. Let C be a linearly convex proper complex cone, and $x, y \in C$. Then, by (2.8), $zx - y \notin C$ iff $\langle f, zx - y \rangle = 0$ for some $f \in C'$. So we have

$$E_C(x,y) = \left\{ \frac{\langle f, y \rangle}{\langle f, x \rangle} : f \in C' \right\}.$$

This gives (2.9) and the triangular inequality then follows from (2.9).

To ensure completeness of our metric, we need a regularity condition on the cone.

Definition 4. Let $K \geq 1$. Following [Rugh07], we say that a complex cone C is of K-bounded sectional aperture if for each vector subspace P of (complex) dimension 2, one may find $m = m_P \in V'$, $m \neq 0$ such that

$$\forall u \in C \cap P, \quad ||m|| \cdot ||u|| \le K|\langle m, u \rangle|. \tag{2.10}$$

In finite dimension, a proper complex cone C is automatically of bounded sectional aperture for some $K \geq 1$ (see [Rugh07], Lemma 8.2).

Lemma 2.2. Let C a proper complex cone of K-bounded sectional aperture.

- 1. For any $x, y \in C$ with ||x|| = ||y|| = 1, there exists $\alpha \in \mathbb{C}$, $|\alpha| = 1$ such that $||\alpha y x|| \le K\delta_C(x, y)$.
- 2. Suppose in addition that C is linearly convex. Then $(C/\sim, \delta_C)$ is a complete metric space, where $x \sim y$ iff $\mathbb{C}^*x = \mathbb{C}^*y$.

Proof. Assume x and y independent and $\delta_C(x,y) < \infty$. Take $m \in V'$, ||m|| = 1 satisfying (2.10) for the vector plane spanned by x and y. Define $x' = x/\langle m, x \rangle$ and $y' = y/\langle m, y \rangle$. One has $1 \in E_C(x', y')$, since otherwise $0 = K|\langle m, x' - y' \rangle| \ge ||x' - y'||$. Let $0 < a < \inf |E_C(x', y')|$ and $b > \sup |E_C(x', y')|$. Then $b, a^{-1} > 1$. Using (2.10),

$$||x' - y'|| \le \frac{b - 1}{b - a} ||ax' - y'|| + \frac{1 - a}{b - a} ||bx' - y'|| \le 2K \frac{(b - 1)(1 - a)}{b - a}$$
$$\le 2K \frac{\sqrt{b} - \sqrt{a}}{\sqrt{b} + \sqrt{a}} = 2K \tanh \frac{\log(b/a)}{4} \le (K/2) \log(b/a).$$

Finally, for some $\alpha \in \mathbb{C}$, $|\alpha| = 1$,

$$\|\alpha y - x\| = \left\| \frac{x'}{\|x'\|} - \frac{y'}{\|y'\|} \right\| \le 2 \frac{\|x' - y'\|}{\max(\|x'\|, \|y'\|)} \le 2\|x' - y'\|.$$

Now, let C be linearly convex, and let (x_n) be a Cauchy sequence for δ_C , with $||x_n|| = 1$. We choose a subsequence (y_n) such that $\delta_C(y_n, y_{n+1}) < 2^{-n}$. By 1, we may rotate inductively y_n in order to have $||y_{n+1} - y_n|| \le K2^{-n}$. Thus, $y_n \to y$, ||y|| = 1, since V is a Banach space. Let us show that $y \in C$. If $\langle g, y \rangle = 0$ for all $g \in C'$ then for $x \in C$ and $\lambda \in \mathbb{C}$, one has $\langle g, x + \lambda y \rangle = \langle g, x \rangle \neq 0$, for all $g \in C'$, hence $x + \lambda y \in C$. This is impossible by properness of C, so we can choose $g_0 \in C'$ such that $\langle g_0, y \rangle \neq 0$. Let $f \in C'$. From (2.9), we have

$$\left| \frac{\langle g_0, y_p \rangle}{\langle g_0, y_n \rangle} \right| \le \exp(\delta_C(y_p, y_n)) \left| \frac{\langle f, y_p \rangle}{\langle f, y_n \rangle} \right|.$$

Letting $p \to \infty$, we see that $\langle f, y \rangle \neq 0$, for all $f \in C'$ so $y \in C$. Finally, δ_C is lower semi-continuous by (2.9). So $\delta_C(y_n, y) \leq \liminf_{p \to \infty} \delta_C(y_n, y_p)$, and $\delta_C(y_n, y) \to 0$. \square

We now come to the contraction principle.

Theorem 2.3. Let V_1 , V_2 be complex Banach spaces, and let $C_1 \subset V_1$, $C_2 \subset V_2$ be proper complex cones (not necessarily linearly convex). Let $T: V_1 \to V_2$ be a linear map, and suppose that $T(C_1 \setminus \{0\}) \subset C_2 \setminus \{0\}$. If the diameter $\Delta = \sup_{x,y \in C_1 \setminus \{0\}} \delta_{C_2}(Tx,Ty)$ is finite, then we have

$$\forall x, y \in C_1, \quad \delta_{C_2}(Tx, Ty) \le \tanh\left(\frac{\Delta}{4}\right) \delta_{C_1}(x, y).$$

Proof. Let $x, y \in C_1 \setminus \{0\}$. We may assume Tx and Ty linearly independent, and $\delta_{C_1}(x,y) < \infty$. If $z \in \mathbb{C}$, and $zx - y \in C_1$ then we have also $zTx - Ty \in C_2$. So

 $E_{C_2}(Tx,Ty) \subset E_{C_1}(x,y)$. Let λ , μ belong to the complement of $E_{C_1}(x,y)$, $\lambda \neq \mu$, and α , $\beta \in E_{C_2}(Tx,Ty)$. So we have

$$\lambda x - y, \ \mu x - y \in C_1, \qquad \alpha Tx - Ty, \ \beta Tx - Ty \notin C_2.$$
 (2.11)

If $z \in \mathbb{C}$, $z \neq 1$, then $z(\lambda Tx - Ty) - (\mu Tx - Ty) \in C_2$ if and only if $h(z)Tx - Ty \in C_2$, where $h(z) = (z\lambda - \mu)/(z-1)$ is a Möbius transformation. We deduce that $h^{-1}E_{C_2}(Tx,Ty) = E_{C_2}(T(\lambda x-y),T(\mu x-y))$. Thus, $(\mu-\alpha)/(\lambda-\alpha)$ and $(\mu-\beta)/(\lambda-\beta)$ both belong to $E_{C_2}(T(\lambda x-y),T(\mu x-y))$. Since $\lambda x-y$, $\mu x-y \in C_1 \setminus \{0\}$, we have $\delta_{C_2}(T(\lambda x-y),T(\mu x-y)) \leq \Delta$. Therefore, we have proved that for arbitrary α , β , $\lambda \neq \mu$ satisfying (2.11)

$$\left| \frac{\mu - \alpha}{\lambda - \alpha} \cdot \frac{\lambda - \beta}{\mu - \beta} \right| \le e^{\Delta}. \tag{2.12}$$

We consider now $M > \sup |E_{C_1}(x,y)|$, and $m < \inf |E_{C_1}(x,y)|$, m > 0. We fix $\alpha, \beta \in E_{C_2}(Tx,Ty)$, we define $A = |\alpha|$, $B = |\beta|$. We assume also that A < B. Since $E_{C_2}(Tx,Ty) \subset E_{C_1}(x,y)$, we have m < A < B < M. Moreover, the whole circles C(0,m) and C(0,M) of center 0 and radius m and M respectively are included in the complement of $E_{C_1}(x,y)$. So we may choose $\mu \in C(0,M)$, $\lambda \in C(0,m)$ to optimize the inequality (2.12). More precisely, we have:

- The Möbius transformation $z \mapsto \frac{z-\beta}{z-\alpha}$ maps the circle C(0,m) onto the circle of center $\frac{\beta \overline{\alpha} m^2}{A^2 m^2}$ and radius $\frac{m|\beta \alpha|}{A^2 m^2}$.
- The Möbius transformation $z\mapsto \frac{z-\alpha}{z-\beta}$ maps the circle C(0,M) onto the circle of center $\frac{M^2-\overline{\beta}\alpha}{M^2-B^2}$ and radius $\frac{M|\beta-\alpha|}{M^2-B^2}$.

Since the element of greatest modulus in the circle of center c and radius r is of modulus |c| + r, (2.12) gives

$$\frac{\left(|\beta\overline{\alpha} - m^2| + m|\beta - \alpha|\right)\left(|M^2 - \overline{\beta}\alpha| + M|\beta - \alpha|\right)}{(A^2 - m^2)(M^2 - B^2)} \le e^{\Delta}.$$

Now we have $|\beta \overline{\alpha} - m^2| + m|\beta - \alpha| \ge AB - m^2 + m(B - A) = (A + m)(B - m)$. In the same way, we find $|M^2 - \overline{\beta}\alpha| + M|\beta - \alpha| \ge (M - A)(M + B)$. So we get

$$\frac{(M-A)(B-m)}{(M-B)(A-m)} \le e^{\Delta}.$$
(2.13)

At this point, we are back to the case of the Hilbert metric. We write $d = \log(B/A) > 0$, $D = \log(M/m) > d$. Consider $\phi(t) = (M-t)(e^dt - m)(M - e^dt)^{-1}(t - m)^{-1}$, with $t \in (m, Me^{-d})$. Then ϕ has a minimum at $t_0 = \sqrt{Mm}e^{-d/2} \in (m, Me^{-d})$. So (2.13) gives

$$\phi(t_0) = \frac{\sinh^2\left(\frac{D+d}{4}\right)}{\sinh^2\left(\frac{D-d}{4}\right)} \le \phi(A) \le e^{\Delta}.$$

This leads to $\tanh(d/4) \leq \tanh(\Delta/4) \tanh(D/4)$, so $d \leq \tanh(\Delta/4)D$ and the conclusion follows.

Remark 1. We proved exactly $\tanh(\delta(Tx,Ty)/4) \leq \tanh(\Delta/4) \tanh(\delta(x,y)/4)$. So, if we define the contraction coefficient of T to be $c(T) = \tanh(\Delta/4)$, then we have $c(TS) \leq c(T)c(S)$.

Example 1. Let C be a closed proper complex cone with non-empty interior, and let also A be a linear map such that $A(C \setminus \{0\}) \subset \text{Int } C$. Suppose that there exists $0 < \rho < 1$, such that $B(Ax, \rho ||Ax||) \subset \text{Int } C$ for all $x \in C \setminus \{0\}$ (such a $\rho > 0$ always exists in finite dimension). Then the δ_C -diameter of AC is bounded by $\Delta = 2\log(1/\rho)$, hence finite. If we assume in addition that C is of K-bounded sectional aperture for some $K \geq 1$ (which is also automatic in finite dimension for a proper cone, see [Rugh07]), then A has a spectral gap. This is proved exactly in the same way as Theorem 3.6 and 3.7 of [Rugh07], replacing the gauge d_C by δ_C , the contraction principle by Theorem 2.3 and using Lemma 2.2, 1. Moreover, the size of the spectral gap is given by $\tanh(\Delta/4) = (1 - \rho)/(1 + \rho)$. We dot not reproduce Rugh's proof.

Suppose now that V is finite dimensional. Then the fact that that A has a spectral gap is the content of Theorem 8.4 of [Rugh07]. However, in this situation, the sets $\hat{\mathbb{C}} \setminus E_C(Ax, Ay)$ might not even be connected, and so one cannot say anything on the d_C -diameter of AC. The technical argument of [Rugh07] does not lead to an explicit and easy estimate of the spectral gap and is simplified by the use of δ_C .

3 The canonical complexification \mathbb{C}^n_+ of \mathbb{R}^n_+

We will denote respectively by $\Re(z)$ and $\Im(z)$ the real and imaginary part of $z \in \mathbb{C}$. Following [Rugh07], we define

$$\mathbb{C}^n_+ = \{ v \in \mathbb{C}^n : \forall k, l, \, \Re(v_k \overline{v_l}) \ge 0 \}. \tag{3.14}$$

 \mathbb{C}^n_+ is a closed complex cone which is obtained from the Birkhoff cone \mathbb{R}^n_+ in a natural way as described in [Rugh07]. The interior of \mathbb{C}^n_+ is given by

Int
$$\mathbb{C}^n_+ = \{ v \in \mathbb{C}^n : \forall k, l, \Re(v_k \overline{v_l}) > 0 \}.$$
 (3.15)

We consider on \mathbb{C}^n the duality $\langle x,y\rangle = \sum x_k y_k$. Our study of \mathbb{C}^n_+ is based on the following two lemmas.

Lemma 3.1. $\mathbb{C}^n_+ \setminus \{0\}$ and Int \mathbb{C}^n_+ are both linearly convex. More precisely, we have

$$x \in \text{Int } \mathbb{C}^n_+ \iff \forall y \in \mathbb{C}^n_+ \setminus \{0\}, \ \langle y, x \rangle \neq 0,$$

$$y \in \mathbb{C}^n_+ \setminus \{0\} \iff \forall x \in \text{Int } \mathbb{C}^n_+, \ \langle y, x \rangle \neq 0.$$
 (3.16)

Proof. Let $x \in \mathbb{C}^n_+ \setminus \{0\}$ and $y \in \operatorname{Int} \mathbb{C}^n_+$. Then, up to multiplying x and y by nonzero complex numbers, we may write $x_k = r_k e^{i\alpha_k}$, $y_k = s_k e^{-i\beta_k}$ where $r_k \geq 0$, $s_k > 0$, $\alpha_k \in [0, \pi/2]$, $\beta_k \in (0, \pi/2)$. Thus, $\Re\langle x, y \rangle = \sum r_k s_k \cos(\alpha_k - \beta_k) > 0$, hence $\langle x, y \rangle \neq 0$. Let $x \in \mathbb{C}^n$ such that $\Re(x_k \overline{x_l}) < 0$ for some $k \neq l$. We define $a = \sum_{j \neq k, l} x_j$. Then for $\epsilon > 0$ sufficiently small, $\Re((\epsilon a + x_k) \overline{x_l}) < 0$. We write $\epsilon a + x_k = r e^{i\alpha}$, $x_l = s e^{i\beta}$ with r, s > 0 and $\mu = \pi - \beta + \alpha \in (-\pi/2, \pi/2)$. We then define $y_k = 1$, $y_l = r s^{-1} e^{i\mu}$ and $y_j = \epsilon$ for $j \neq k, l$. Then $y \in \operatorname{Int} \mathbb{C}^n_+$ and $\langle x, y \rangle = 0$. This proves the second part of (3.16). The first part is proved essentially in the same way.

Lemma 3.2. Let $x, y \in \text{Int } \mathbb{C}^n_+$. Then

$$E_{\operatorname{Int}\mathbb{C}^n_+} = \bigcup_{k,l} \overline{D}_{kl}(x,y)$$

where $\overline{D}_{kl} = \overline{D}_{kl}(x,y)$ is the closed disk of center $c_{kl}(x,y)$ and radius $r_{kl}(x,y)$. c_{kl} and r_{kl} are given by

$$c_{kl}(x,y) = \frac{\overline{x_l}y_k + \overline{x_k}y_l}{2\Re(x_k\overline{x_l})}, \quad r_{kl}(x,y) = \frac{|x_ly_k - x_ky_l|}{2\Re(x_k\overline{x_l})}.$$
 (3.17)

Proof. Let $z \in \mathbb{C}$. Then, $z \in E_{\text{Int }\mathbb{C}^n_+}(x,y)$ if and only if there exist k and l such that

$$\Re((zx_l - y_l)\overline{(zx_k - y_k)}) \le 0. \tag{3.18}$$

If k and l are such that $x_l y_k - x_k y_l = 0$, then \overline{D}_{kl} reduces to $\{y_k/x_k\}$ and the only z satisfying (3.18) is y_k/x_k . If k and l are such that $x_l y_k - x_k y_l \neq 0$ then

$$\Re((zx_l - y_l)\overline{(zx_k - y_k)}) \le 0 \quad \iff \quad \varphi_{kl}^{-1}(z) \in P = \{w : \Re(w) \ge 0\} \cup \{\infty\},\$$

where $z = \varphi_{kl}(w)$ is the Möbius tranformation defined by

$$\varphi_{kl}(w) = \frac{wy_k + y_l}{wx_k + x_l}, \quad \varphi_{kl}^{-1}(z) = \frac{zx_l - y_l}{-zx_k + y_k}.$$

Thus the complex numbers z satisfying (3.18) are exactly the elements of $\overline{D}_{kl} = \varphi_{kl}(P)$. A brief computation then leads to the given formulas for c_{kl} and r_{kl} .

We study now the $n \times n$ matrices A satisfying

$$A(\mathbb{C}^n_+ \setminus \{0\}) \subset \text{Int } \mathbb{C}^n_+.$$
 (3.19)

By Lemma 3.1, (3.19) is satisfied if and only if $\langle Ax, y \rangle \neq 0$ for all $x, y \in \mathbb{C}^n_+ \setminus \{0\}$. So the set of all matrices A satisfying (3.19) is itself a linearly convex complex cone. Moreover, Lemma 3.1 also implies that if A satisfies (3.19) then so does its transpose matrix tA .

Proposition 3.3. Let $A = (a_{ij})_{1 \leq i,j \leq n}$ be a $n \times n$ complex matrix. Then $A(\mathbb{C}^n_+ \setminus \{0\}) \subset \mathbb{C}^n_+$ if and only if for all indices k, l, p, q

$$\Re(\overline{a_{kp}}a_{lq} + \overline{a_{kq}}a_{lp}) > |a_{kp}a_{lq} - a_{kq}a_{lp}|. \tag{3.20}$$

Proof. Let us denote by $\lambda_1, \dots, \lambda_n$ the lines of A. Suppose that (3.19) holds. Then for $x \in \mathbb{C}^n_+ \setminus \{0\}$, we have

$$Ax = (\langle \lambda_1, x \rangle, \cdots, \langle \lambda_n, x \rangle) \in \text{Int } \mathbb{C}^n_+$$

So, $\langle \lambda_j, x \rangle \neq 0$ for all $x \in \mathbb{C}^n_+ \setminus \{0\}$ and Lemma 3.1 implies that $\lambda_j \in \text{Int } \mathbb{C}^n_+$.

Consider now a matrix A such that $\lambda_j \in \text{Int } \mathbb{C}^n_+$ for all indices j. Then (3.19) holds if and only if for all indices k, l and all $x \in \mathbb{C}^n_+ \setminus \{0\}$ we have $\Re(\overline{\langle \lambda_k, x \rangle} \langle \lambda_l, x \rangle) > 0$ or

equivalently $\Re(\langle \lambda_l, x \rangle / \langle \lambda_k, x \rangle) > 0$. By Lemma 3.1 (see also the proof of Lemma 2.1), for fixed k and l, the set of all $\langle \lambda_l, x \rangle / \langle \lambda_k, x \rangle$ is exactly $E_{\text{Int } \mathbb{C}^n_+}(\lambda_k, \lambda_l)$. So (3.19) holds if and only if for all indices k, l we have

$$E_{\operatorname{Int} \mathbb{C}^n_{\perp}}(\lambda_k, \lambda_l) \subset \{z \in \mathbb{C} : \Re(z) > 0\}.$$

By Proposition 3.2, we have $E_{\text{Int }\mathbb{C}_+^n}(\lambda_k, \lambda_l) = \bigcup \overline{D}_{pq}(\lambda_k, \lambda_l)$. $\overline{D}_{pq}(\lambda_k, \lambda_l)$ is the closed disk of center $c_{pq}(\lambda_k, \lambda_l)$ and radius $r_{pq}(\lambda_k, \lambda_l)$ where

$$c_{pq}(\lambda_k, \lambda_l) = \frac{\overline{a_{kp}} a_{lq} + \overline{a_{kq}} a_{lp}}{2\Re(a_{kp} \overline{a_{kq}})}, \quad r_{pq}(\lambda_k, \lambda_l) = \frac{|a_{kp} a_{lq} - a_{kq} a_{lp}|}{2\Re(a_{kp} \overline{a_{kq}})}.$$
(3.21)

Now, (3.19) holds if and only if for all indices k, l, p, q, one has

$$\Re(c_{pq}(\lambda_k, \lambda_l)) > r_{pq}(\lambda_k, \lambda_l),$$

which provides the desired formula. Finally, observe that if (3.20) is satisfied for all indices, then letting k = l = j, we have $\lambda_j \in \text{Int } \mathbb{C}^n_+$.

Corollary 3.4. If a complex $n \times n$ matrix A satisfies (3.20) then A has a spectral gap. Proof. This is a direct consequence of Theorem 8.4 of [Rugh07]. See also Example 1.

We give now explicit estimates for the δ -diameter of $A(\mathbb{C}^n_+ \setminus \{0\})$.

Proposition 3.5. Let A be a complex $n \times n$ matrix such that $A(\mathbb{C}^n_+ \setminus \{0\}) \subset \operatorname{Int} \mathbb{C}^n_+$. Denote by $\lambda_1,...,\lambda_n$ the lines of A. Define

$$\Delta_1 = \max_{k,l} \delta(\lambda_k, \lambda_l), \quad \Delta_2 = \max_{k,l} \operatorname{diam}_{RHP} E_{\operatorname{Int}} \,_{\mathbb{C}^n_+}(\lambda_k, \lambda_l),$$

where $\operatorname{diam}_{RHP}$ denotes the diameter with respect to the Poincaré metric of the right half plane. Then the δ -diameter δ -diam $(A(\mathbb{C}^n_+ \setminus \{0\}))$ satisfies

$$\max(\Delta_1, \Delta_2) \leq \delta$$
-diam $(A(\mathbb{C}^n_+ \setminus \{0\})) \leq \Delta_1 + 2\Delta_2$.

Proof. We denote by Δ the δ -diameter of $A(\mathbb{C}^n_+ \setminus \{0\})$. We denote also by $\rho(a,b)$ the Poincaré metric in the right half plane: for a, b with $\Re(a), \Re(b) > 0$

$$\rho(a,b) = \log \frac{|a+\overline{b}| + |a-b|}{|a+\overline{b}| - |a-b|} \ge \log \frac{\Re(b)}{\Re(a)}.$$
(3.22)

Consider two vectors u and $v \in \text{Int } \mathbb{C}^n_+$. Then from the description given by Proposition 3.2, one has

$$\delta(u,v) = \log \frac{\max_{k,l} \left\{ \left(|\overline{u_k}v_l + \overline{u_l}v_k| + |u_kv_l - u_lv_k| \right) \left(2\Re(\overline{u_k}u_l) \right)^{-1} \right\}}{\min_{k,l} \left\{ \left(|\overline{u_k}v_l + \overline{u_l}v_k| - |u_kv_l - u_lv_k| \right) \left(2\Re(\overline{u_k}u_l) \right)^{-1} \right\}}$$
(3.23)

$$= \max_{k,l,p,q} \log \frac{|u_p v_k|}{|u_k v_p|} \frac{\Re\left(\frac{u_q}{u_p}\right)}{\Re\left(\frac{u_l}{u_k}\right)} \frac{\left|\frac{v_l}{v_k} + \frac{\overline{u_l}}{\overline{u_k}}\right| + \left|\frac{v_l}{v_k} - \frac{u_l}{u_k}\right|}{\left|\frac{v_q}{v_p} + \frac{\overline{u_q}}{\overline{u_p}}\right| - \left|\frac{v_q}{v_p} - \frac{u_q}{u_p}\right|}$$
(3.24)

$$\leq \max_{k,l,p,q} \left\{ \rho\left(\frac{v_l}{v_k}, \frac{u_l}{u_k}\right) + \rho\left(\frac{v_q}{v_p}, \frac{u_q}{u_p}\right) + \log\left|\frac{v_k u_p}{u_k v_p}\right| \right\}. \tag{3.25}$$

We used in (3.25) inequality (3.22) and the following straightforward identity

$$\frac{\Re(d)}{\Re(b)} \frac{|a+\overline{b}| + |a-b|}{|c+\overline{d}| - |c-d|} = \sqrt{\frac{\Re(a)\Re(d)}{\Re(b)\Re(c)}} \exp\left(\frac{1}{2}\rho(a,b) + \frac{1}{2}\rho(c,d)\right).$$

Let $x \ y \in \mathbb{C}^n_+ \setminus \{0\}$. We define u = Ax and v = Ay. Thus $u_j = \langle \lambda_j, x \rangle$ and $v_j = \langle \lambda_j, y \rangle$. The ratios u_l/u_k and v_l/v_k belong to $E_{\text{Int }\mathbb{C}^n_+}(\lambda_k, \lambda_l)$. Therefore, letting $p = k, \ q = l$ in (3.24) we get $\Delta \geq \Delta_2$. We have obviously $\Delta \geq \Delta_1$ so the lower bound follows. The upper bound is a consequence of inequality (3.25) and the formula for $\delta(\lambda_k, \lambda_p)$ given by Lemma 2.1.

Remark 2. The formula (3.23) given in the preceding proposition shows that the projective metric $\delta_{\mathbb{C}^n_+}$ extends the Hilbert metric $h_{\mathbb{R}^n_+}$ on \mathbb{R}^n_+ . This is also the case for the hyperbolic gauge of Rugh. So, $\delta_{\mathbb{C}^n_+}$ is another possible extension of the Hilbert metric.

Theorem 3.6. Let $\theta \in (0,1)$, and $\sigma > 1$. Consider a complex matrix A such that for all indices

$$\Re(\overline{a_{kp}}a_{lq} + \overline{a_{kq}}a_{lp}) > \frac{1}{\theta}|a_{kp}a_{lq} - a_{kq}a_{lp}|,$$
$$|a_{kp}a_{lq}| \leq \sigma^{2}|a_{kq}a_{lp}|.$$

Then $A(\mathbb{C}^n_+ \setminus \{0\}) \subset \text{Int } C^n_+$, and we have

$$\delta$$
-diam $A(\mathbb{C}^n_+ \setminus \{0\}) \le 8 \log \frac{1+\theta}{1-\theta} + 2 \log \sigma$.

Proof. We use the same notations as in the proceeding propositions. We want first to estimate Δ_2 . We have

$$E_{\text{Int }C_+^n}(\lambda_k,\lambda_l) = \bigcup_{p,q} \overline{D}_{pq}(\lambda_k,\lambda_l).$$

Moreover, the complex numbers a_{lp}/a_{kp} and a_{lq}/a_{kq} both belong to \overline{D}_{pq} . So the disk \overline{D}_{pq} intersects the disk \overline{D}_{qr} which in turn intersects \overline{D}_{rs} . We deduce that

$$\Delta_2 \leq 3 \max_{k,l,p,q} \operatorname{diam}_{\mathrm{RPH}} \overline{D}_{p,q}(\lambda_k, \lambda_l).$$

Moreover, the diameter of a closed disk $\overline{D} \subset \{\Re(z) > 0\}$ of center c and radius r > 0 for the Poincaré metric ρ is

$$\rho(c-r, c+r) = \log \frac{\Re(c) + r}{\Re(c) - r}.$$

So by (3.21), $\Delta_2 \leq 3 \log((1+\theta)/(1-\theta))$. Finally, we apply inequality (3.25) to $u = \lambda_i$, $v = \lambda_i$ and we find that

$$\Delta_1 \le 2\log\frac{1+\theta}{1-\theta} + 2\log\sigma.$$

(One checks directly that $\rho(a_{il}/a_{jk}, a_{il}/a_{ik}) \leq \log((1+\theta)/(1-\theta))$.)

4 More general complex cones

We will compare in section 5 the metric δ_C with the hyperbolic gauge d_C . As mentionned in the introduction, one cannot hope any control of d_C by δ_C in a general complex cone. Our main goal is to show (in section 5) that such a control is possible at least for canonical complexification of real Birkhoff cones as defined in [Rugh07]. We fix here the setting and prove the various lemmas needed in section 5.

Recall the definition of the canonical complexification. Let $V_{\mathbb{R}}$ a real Banach space, and consider its complexification $V = V_{\mathbb{R}} \oplus i V_{\mathbb{R}}$. It is a complex Banach space. Let $C_{\mathbb{R}} \subset V_{\mathbb{R}}$ a real Bikhoff cone and $C'_{\mathbb{R}} \subset V'_{\mathbb{R}}$ its dual. Each real linear functional on $V_{\mathbb{R}}$ naturally extends to a complex linear functional on V, and the canonical complexification is defined by

$$C = \{ x \in V : \forall m, l \in C_{\mathbb{R}}', \Re(\langle m, x \rangle \overline{\langle l, x \rangle}) \ge 0 \}.$$

It may also be defined as $C = \mathbb{C}^*(C_{\mathbb{R}} + iC_{\mathbb{R}})$.

So we naturally consider the slightly more general situation of a cone C in a general complex Banach space V satisfying

$$C = \{ x \in V : \forall m, l \in S, \Re(\langle m, x \rangle \overline{\langle l, x \rangle}) \ge 0 \}, \tag{4.26}$$

for some non-empty subset S of V'.

Lemma 4.1. Let C satisfy (4.26). Define

$$\mathcal{F}(x,y) = \{ (m,l) \in S : \langle m, y \rangle \langle l, x \rangle - \langle l, y \rangle \langle m, x \rangle \neq 0 \}.$$

(It may be an empty set) For each $(m,l) \in \mathcal{F}(x,y)$, we define also the associated open disk or open half-plane

$$D_{m,l}(x,y) = \varphi_{ml}(\{w : \Re(w) > 0\}), \quad \phi_{ml}(w) = \frac{w\langle m, y \rangle + \langle l, y \rangle}{w\langle m, x \rangle + \langle l, x \rangle}. \tag{4.27}$$

Then $E(x,y) = \bigcup D_{m,l}(x,y)$, where the union is taken over all $(m,l) \in \mathcal{F}(x,y)$.

Proof. The proof is essentially the same as the proof of Lemma 3.2. \Box

We will denote by \mathcal{Q} the first quadrant of the complex plane: $\mathcal{Q} = \{z \in \mathbb{C} : \Re(z) \geq 0 \text{ and } \Im(z) \geq 0\}$. In what follows, we consider a complex Banach space V. We consider a closed *convex cone* $R \subset V$, that is, a closed non-empty subset such that $R + R \subset R$ and $(0, \infty)R \subset R$. We consider also a complex cone $C \subset V$ satisfying

Condition C1. $C = \mathbb{C}^*R$, and $\overline{(R+iR)} \cap \overline{(R-iR)} = R$. In particular, C is closed.

Condition C2. C is proper and contains at least two (complex) independent vectors.

We define also $S = \{m \in V' : \forall x \in R, \langle m, x \rangle \in \mathcal{Q}\}$. It is a closed convex cone.

Lemma 4.2. Let C and R satisfy (C1). Then we have

$$R = \{x \in V : \forall m \in S, \langle m, x \rangle \in \mathcal{Q}\}, \tag{4.28}$$

$$C = \mathbb{C}^* R = \{ x \in V : \forall m, l \in S, \Re\left(\langle m, x \rangle \overline{\langle l, x \rangle}\right) \ge 0 \}.$$
 (4.29)

Proof. Let $x \in V$. If $x \in \overline{(R-iR)}$, then $\Re\langle m, x \rangle \geq 0$, $\forall m \in S$. Conversely, $\overline{(R-iR)}$ is a closed convex cone. So, if $x \notin \overline{(R-iR)}$, by Mazur's theorem, there exists $m \in V'$ such that $\Re\langle m, x \rangle < 0$; and such that $\Re\langle m, y \rangle \geq 0$, $\forall y \in \overline{(R-iR)}$, or equivalently, $m \in S$.

Now, $\langle m, x \rangle \in \mathcal{Q}$ if and only if $\Im \langle m, x \rangle = \Re(\langle m, -ix \rangle) \geq 0$ and $\Re \langle m, x \rangle \geq 0$. Thus, $x \in V$ satisfies $\langle m, x \rangle \in \mathcal{Q}$ for all $m \in S$ if and only if x and -ix both belong to $\overline{(R-iR)}$. Hence, by (C1), if and only if $x \in R$. This gives (4.28).

Finally, let $x \in V$. Then $\Re(\langle m, x \rangle \overline{\langle l, x \rangle}) \geq 0$ for all $m, l \in S$ if and only if the argument of $\langle m, x \rangle$ (when $\langle m, x \rangle$ is non-zero) varies within a $\pi/2$ angle. In other words, if and only if one may find $\alpha \in \mathbb{C}^*$ such that $\langle m, \alpha x \rangle \in \mathcal{Q}$ for all $m \in S$. (4.29) then follows from (4.28).

Example 2. As regards the canonical complexification of a real Birkhoff cone, one takes $R = C_{\mathbb{R}} + iC_{\mathbb{R}}$, and (C1) is a consequence of the convexity of $C_{\mathbb{R}}$. Another example is provided by

$$C = \{ x \in V : \|x - \langle \mu, x \rangle a\| \le \sigma |\langle \mu, x \rangle| \cdot \|a\| \}, \tag{4.30}$$

where $\sigma > 0$, $a \in V$ and $\mu \in V'$ such that $\langle \mu, a \rangle = 1$ (μ is a *complex* linear functional). Here, one takes $R = \{x \in C : \langle \mu, x \rangle \in [0, \infty)\}$. The Remark 3.10 in [Rugh07] says that a bounded linear operator T on a complex Banach space has a spectral gap if and only if it is a strict contraction of a cone like (4.30) (but with another norm).

Remark 3. The condition (C2) implies that the cone R satisfies $R \cap (-R) \subset \{0\}$, and so is proper as a convex cone. Indeed, let $x \in R \cap (-R)$. Then for all $m \in S$, $\langle m, x \rangle = 0$. By (4.29), this implies that $\forall y \in C$, $\forall z, z' \in \mathbb{C}$, $zx + z'y \in C$. By (C2), we find that x must be 0. We mention also the following consequence of (C2). Given $x, y \in C$ complex linearly independent, we can find $m \in S$ such that $\langle m, x \rangle \neq 0$ (by properness of R and(4.28)). But then, $y - (\langle m, y \rangle / \langle m, x \rangle)x \neq 0$ and we can find again $l \in S$ not vanishing on this vector. This proves that $\mathcal{F}(x, y) \neq \emptyset$.

Remark 4. The cone C need not be linearly convex (even though one can show that Int C is). However, δ_C satisfies the triangular inequality on C. Indeed, using Lemma 4.1, one can show that the formula of Lemma 2.1 remains valid if we replace $f \in C'$ by $f \in S + iS$, $\langle f, x \rangle$, $\langle f, y \rangle \neq 0$. This is because each $D_{m,l}$ is an open finite disk or a half plane and $0 \notin D_{m,l}$. So the supremum and the infimum of |z| are both attained on the boundary of $D_{m,l}$. We skip the details.

Definition 5. Let $x, y \in C \setminus \{0\}$. We define $L(x, y) = \{z \in \hat{\mathbb{C}} : zx - y \in C\}$, with the convention that $\infty \in L(x, y)$.

Lemma 4.3. Let $x, y \in C \setminus \{0\}$ and suppose that $0, \infty$ are in the interior of L(x, y) in $\hat{\mathbb{C}}$ (denoted by $\mathring{L}(x,y)$). Then each $D_{m,l}$, $(m,l) \in \mathcal{F}(x,y)$ is an open finite disk. Moreover, the closed convex hull of the centers $c_{m,l}$ is included in the closure $\overline{E}(x,y)$ of E(x,y). In general, we can say that as soon as $\mathring{L}(x,y)$ is not empty, it is a simply connected open subset of $\hat{\mathbb{C}}$.

Proof. Since $\phi_{m,l}$ given by (4.27) is a Möbius transformation, it maps the open half plane $\{\Re(w) > 0\}$ onto an open finite disk, an open half plane or the complement (in $\hat{\mathbb{C}}$) of a closed finite disk. Since $0, \infty \in \mathring{L}(x,y)$, each $D_{m,l}$ must be an open finite disk, and $\phi_{m,l}^{-1}(\infty) \notin \{\Re(w) \geq 0\} \cup \{\infty\}$. So $\Re(\langle m, x \rangle \overline{\langle l, x \rangle}) > 0$, and we get the following formula for the center $c_{m,l}$.

$$c_{m,l} = \frac{\overline{\langle l, x \rangle} \langle m, y \rangle + \overline{\langle m, x \rangle} \langle l, y \rangle}{2\Re \left(\langle m, x \rangle \overline{\langle l, x \rangle} \right)}.$$
 (4.31)

Now, let $A \subset \mathcal{F}(x,y)$ be finite and for $(m,l) \in A$, let $t_{m,l} \geq 0$, $\sum t_{m,l} = 1$. We may assume A symmetric, i.e. $(m,l) \in A$ iff $(l,m) \in A$. Then the complex number $z = \sum_{(m,l) \in A} t_{m,l} c_{m,l}$ satisfies $z = \langle f, y \rangle$ where $f \in V'$ is defined by

$$\forall v \in V, \quad \langle f, v \rangle = \sum_{(m,l) \in A} \frac{(t_{m,l} + t_{l,m})\overline{\langle l, x \rangle}}{2\Re\left(\langle m, x \rangle \overline{\langle l, x \rangle}\right)} \langle m, v \rangle. \tag{4.32}$$

We observe that $\langle f, x \rangle = 1$ so that $\langle f, zx - y \rangle = 0$.

Define $S_0 = \{l \in V' : \exists m \in V', (m,l) \in A\}$, the finite set of all the linear functionals l appearing in (4.32). We suppose first that for all $l, l' \in S_0$, we have $\Re(\langle l, x \rangle \overline{\langle l', x \rangle}) > 0$. Then, we can find $\beta \in \mathbb{C}^*$ such that for all $l \in S_0$, $\beta \langle l, x \rangle$ belongs to the interior of \mathcal{Q} . Let $u \in R$, and suppose that $\langle f, u \rangle = 0$. Taking real parts in (4.32) with $v = \overline{\beta}u$, we see that as soon as $t_{m,l} + t_{l,m} > 0$, we have $\langle m, u \rangle = 0$, and by symmetry, $\langle l, u \rangle = 0$. Now, we observe that for all $(m, l) \in \mathcal{F}$, one cannot have simultaneously $\langle m, zx - y \rangle = 0$ and $\langle l, zx - y \rangle = 0$. Since $\langle f, zx - y \rangle = 0$, we deduce that $zx - y \notin C = \mathbb{C}^*R$. This proves that $z \in E(x, y)$.

We consider now the general case. We fix $\mu \in S$ such that $\langle \mu, x \rangle \neq 0$ (possible by properness of R). If $\epsilon > 0$ and $m \in S$, we define $m_{\epsilon} = m + \epsilon \mu \in S$. A direct calculation then shows that for all $l, l' \in S$, $\Re(\langle l_{\epsilon}, x \rangle \overline{\langle l'_{\epsilon}, x \rangle}) \geq \epsilon^2 |\langle \mu, x \rangle|^2 > 0$. From the preceding discussion, we deduce that $z_{\epsilon} = \sum_{(m,l)\in A} t_{m,l} c_{m_{\epsilon},l_{\epsilon}}$ belong to E(x,y), and letting $\epsilon \to 0$, $z \in \overline{E(x,y)}$. So the closed convex hull K of the $c_{m,l}$ is a compact convex subset of $\overline{E(x,y)}$.

Now, consider the euclidean projection p on this closed convex set K. If $z \in E(x,y)$, then the entire segment $[z,p(z)] \subset E(x,y)$. Indeed, z belongs to some open disk $D_{m,l}$, and since $c_{m,l} \in K$ we have the following angular condition: $\Re((z-p(z)) \cdot \overline{(c_{m,l}-p(z))}) \leq 0$, from which we deduce that $|z-c_{m,l}|^2 \geq |p(z)-c_{m,l}|^2$. Hence, p(z) belongs also to $D_{m,l}$ which is convex and thus contains [z,p(z)]. Since p is continuous, we deduce that if $z \in \overline{E(x,y)}$, then $[z,p(z)] \subset \overline{E(x,y)}$. Therefore, if $z \in \mathring{L}(x,y)$ the halfline $z + \mathbb{R}_+(z-p(z)) \subset \mathring{L}(x,y)$. It is now easy to see that every loop in $\mathring{L}(x,y)$ with base point ∞ is homotopic to the constant loop at ∞ .

In general, if $L(x,y) \neq \emptyset$ and if $\alpha, \beta \in L(x,y), \alpha \neq \beta$, then the Möbius tranformation $z \mapsto (z\alpha - \beta)/(z-1)$ maps $L(\alpha x - y, \beta x - y)$ onto L(x,y), and $0, \infty \in L(\alpha x - y, \beta x - y)$. Thus, L(x,y) is also simply connected.

Remark 5. Let $\Omega \subset V$ be an open complex cone. We consider the projective space $PV = V \setminus \{0\}/\sim$ associated to V (where $x \sim y$ iff $\mathbb{C}x = \mathbb{C}y$), and the open subset

 $P\Omega \subset PV$ associated to Ω . The open set $P\Omega \subset PV$ is said to be \mathbb{C} -convex (see [An04]) if its intersection with any projective complex line L is simply connected and $\neq L$. We refer to [An04] for historical notes and more about \mathbb{C} -convexity. It is interesting to mention that, in general, \mathbb{C} -convexity implies linear convexity for open sets. See for instance [Hor94] or [An04] for a proof in finite dimension. This result has been extended recently to complex Banach spaces in [Fl06]. In our situation, we mention without proof that when non-empty, Int C is \mathbb{C} -convex, and linearly convex. (This is not actually a direct consequence of the preceding lemma: one has to prove that $L_{\text{Int }C}(x,y) = \mathring{L}_C(x,y)$.)

5 Comparisons of metrics

In this section, we consider a complex cone C satisfying conditions (C1)-(C2) of section 4. In our setting, the complex gauge $d_C(x,y)$ of Rugh (cf. [Rugh07]) is defined as follows.

Definition 6 (Rugh). 1. If x and y are colinear then $d_C(x,y) = 0$.

- 2. If x and y are (complex) linearly independent and if L(x, y) contains 0 and ∞ , then $d_C(x, y) = d_{\mathring{L}(x, y)}(0, \infty)$ is the Poincaré distance (see e.g. [Mil06]) between 0 and ∞ in the hyperbolic Riemann surface $\mathring{L}(x, y)$. Note that our case, properness of the cone implies that $\mathring{L}(x, y)$ avoids at least three points and hence is hyperbolic. As a normalization, we consider the Poincaré metric with Gaussian curvature -1 (thus, on the unit disk, it is $2|dz|/(1-|z|^2)$).
- 3. $d_C(x,y) = \infty$ otherwise.

The gauge d_C does not satisfy the triangular inequality in general, even if the cone C satisfy condition (C1)-(C2). So we consider as in [Rugh07] the following projective pseudo-metric.

Definition 7.
$$\tilde{d}_C(x,y) = \inf\{\sum d_C(x_k, x_{k+1}) : x_0 = x, x_1, \dots, x_n = y \in C \setminus \{0\}\}.$$

One always has $\tilde{d}_C(x,y) \leq d_C(x,y)$.

By Proposition 4.3, when non-empty, $\check{L}(x,y)$ is simply connected. As an interesting consequence, we may use the improved contraction constant in Lemma 2.4 of [Rugh07]. More precisely, we have: (see [Rugh07], Lemma 2.4 and Remark 2.5)

Theorem 5.1 (Rugh). Let $T: V_1 \to V_2$ be a complex linear map. Let $C_1 \subset V_1$, $C_2 \subset V_2$ satisfy (C1) and (C2), and such that $T(C_1 \setminus \{0\}) \subset C_2 \setminus \{0\}$. Assume that the diameter $\Delta = diam_{C_2}T(C_1 \setminus \{0\})$ is finite, then we have

$$\forall x, y \in C_1 \setminus \{0\}, \quad d_{C_2}(Tx, Ty) \le \tanh\left(\frac{\Delta}{2}\right) d_{C_1}(x, y).$$

Now, we compare d_C , \tilde{d}_C and δ_C on a complex cone satisfying (C1)-(C2). First of all, let us remark that δ_C is different from \tilde{d}_C (and d_C). For instance, in \mathbb{C}^3_+ , E(x,y) may look like figure 1, where we took

$$x = (1, e^{-i\pi/12}, e^{i\pi/12})$$
 and $y = (2 + e^{i\pi/3}, (2 - i)e^{-i\pi/12}, (3 - i)e^{i\pi/12}).$ (5.33)

In this case, $\delta_C(x,y) > d_C(x,y) \geq \tilde{d}_C(x,y)$ since increasing a domain decreases hyperbolic distances (observe that $\log(b/a)$ is the Poincaré distance between 0 and ∞ in $\hat{\mathbb{C}} \setminus D$ where D is the closed disk of diameter [a,b]).

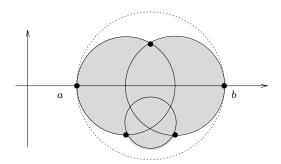


Figure 1: A counter example.

Proposition 5.2. We have $\forall x, y \in C \setminus \{0\}, \frac{1}{2}\delta_C(x,y) \leq d_C(x,y)$.

Proof. We may assume that $d_C(x,y) < \infty$, and that x and y are linearly independent. Then $0, \infty \in \mathring{L}(x,y)$. Denote by $a = \inf |E(x,y)| > 0$ and $b = \sup |E(x,y)| < \infty$. Let $z_0, z_1 \in E(x,y), z_0 \neq z_1$. We can write $z_k = \phi_{m_k,l_k}(w_k)$, where $\phi_{m,l}$ is defined by (4.27), and $(m_k,l_k) \in \mathcal{F}(x,y), k = 0,1$. We have $\Re(w_k) > 0$ and possibly after replacing w_k by w_k^{-1} and exchanging m_k and l_k , we may assume also that $\Im(w_k) \geq 0$. We define $f_k = w_k m_k + l_k$, so that $z_k = \langle f_k, y \rangle / \langle f_k, x \rangle, k = 0,1$. For $t \in (0,1)$, we define also

$$f_t = (1-t)f_0 + tf_1 = (1-t)w_0m_0 + tw_1m_1 + (1-t)l_0 + tl_1.$$

Observe that $(1-t)w_0$, tw_1 , (1-t) and t all belong to $\{w \in \mathbb{C} : \Re(w) > 0 \text{ and } \Im(w) \ge 0\}$. So, if $v \in C$ and $\langle f_t, v \rangle = 0$ then $\langle m_k, v \rangle = 0$, $\langle l_k, v \rangle = 0$ (k = 0, 1). Thus, $\langle f_t, x \rangle \ne 0$ for all $t \in [0, 1]$, and we may define $z_t = \langle f_t, y \rangle / \langle f_t, x \rangle$. Then, for all $t \in (0, 1)$, $z_t \in \overline{E(x, y)}$. Indeed, if this is not true, then $z_t x - y \in C$. But $\langle f_t, z_t x - y \rangle = 0$ so we have for instance $\langle m_0, z_t x - y \rangle = 0$ and $\langle m_0, x \rangle \ne 0$. Hence $z_t = \langle m_0, y \rangle / \langle m_0, x \rangle \in \overline{E(x, y)}$ by Proposition 4.1, and this is a contradiction.

Therefore, we have a circular arc $t \mapsto z_t$, $t \in [0,1]$, with values in $\overline{E(x,y)}$. Denote by Γ its range. It is a compact set containing more than three points (since $z_0 \neq z_1$) and not containing 0 and ∞ . Increasing a domain decreases hyperbolic distances, thus

$$d_{\hat{\mathbb{C}}\backslash\Gamma}(0,\infty) \le d_{\mathring{L}(x,y)}(0,\infty) = d_C(x,y). \tag{5.34}$$

Now, the Möbius transformation

$$\varphi(z) = \frac{z\langle f_0, x \rangle - \langle f_0, y \rangle}{z\langle f_1, x \rangle - \langle f_1, y \rangle}$$
(5.35)

induces a conformal isomorphism from $\hat{\mathbb{C}} \setminus \Gamma$ onto $\mathbb{C} \setminus \mathbb{R}_{-}$; and the map

$$\lambda \mapsto \frac{2\sqrt{\lambda} - 1}{2\sqrt{\lambda} + 1}, \quad \sqrt{\lambda} \text{ such that } \Re(\sqrt{\lambda}) > 0,$$

is a conformal isomorphism from $\mathbb{C} \setminus \mathbb{R}_{-}$ onto the open unit disk in \mathbb{C} . We deduce from this, that if $\lambda, \mu \in \mathbb{C} \setminus \mathbb{R}_{-}$, and $|\lambda| \geq |\mu|$, then

$$\tanh\left(\frac{d_{\mathbb{C}\backslash\mathbb{R}-}(\lambda,\mu)}{2}\right) = \left|\frac{\sqrt{\lambda}-\sqrt{\mu}}{\sqrt{\lambda}+\sqrt{\mu}}\right| \ge \frac{|\sqrt{\lambda}|-|\sqrt{\mu}|}{|\sqrt{\lambda}|+|\sqrt{\mu}|}, \text{ and}$$
$$d_{\mathbb{C}\backslash\mathbb{R}-}(\lambda,\mu) \ge \log\frac{\sqrt{|\lambda|}}{\sqrt{|\mu|}} = \frac{1}{2}\log\frac{|\lambda|}{|\mu|}.$$

Using the Möbius transformation (5.35), we find

$$d_{\hat{\mathbb{C}}\backslash\Gamma}(0,\infty) = d_{\mathbb{C}\backslash\mathbb{R}_{-}}\left(\frac{\langle f_{0},y\rangle}{\langle f_{1},y\rangle},\frac{\langle f_{0},x\rangle}{\langle f_{1},x\rangle}\right) \geq \frac{1}{2}\log\left|\frac{\langle f_{0},y\rangle\langle f_{1},x\rangle}{\langle f_{1},y\rangle\langle f_{0},x\rangle}\right| = \frac{1}{2}\log\frac{|z_{0}|}{|z_{1}|}.$$

Combining with (5.34) and the definition of δ_C , the result follows.

Corollary 5.3. Under the same assumptions, \tilde{d}_C does not degenerate and we have

$$\forall x, y \in C \setminus \{0\}, \quad \frac{1}{2}\delta_C(x,y) \le \tilde{d}_C(x,y).$$

Proof. This is a consequence of the definition of \tilde{d}_C and the preceding proposition.

To get an upper bound for $d_C(x, y)$, we proceed in two steps. First, we consider the case when x and y are δ_C -close to each other and then we consider the general case.

Lemma 5.4. There exists a constant $\delta_0 > 0$ (not depending on the cone) such that if $x, y \in C \setminus \{0\}$ and if

$$\delta_C(x,y) < \delta_0,$$

then

$$\tilde{d}_C(x,y) \le d_C(x,y) \le 3\delta_C(x,y).$$

Proof. First, we consider $\alpha > 1$ and 0 < a < b. Let $\Omega_{\alpha} \subset \hat{\mathbb{C}}$ be the complement (in $\hat{\mathbb{C}}$) of the union of the two closed disks passing through a and b and intersecting the real axis at an angle $\pi/(2\alpha)$ (see figure 2). Then the Poincaré distance in Ω_{α} between 0 and ∞ is given by:

$$d_{\Omega_{\alpha}}(0,\infty) = \alpha \log \frac{b}{a}.$$
 (5.36)

Indeed, the transformation

$$f(z) = \left(\frac{z\sqrt{b} - a\sqrt{b}}{z\sqrt{a} - b\sqrt{a}}\right)^{\alpha}$$

is a conformal isomorphism from Ω_{α} to the right half-plane. The Poincaré metric on the right half-plane is given by $|dz|/\Re(z)$. Since $f(0) = f(\infty)^{-1}$ and $f(\infty) = (b/a)^{\alpha/2}$, equation (5.36) follows.

Now, let $x, y \in C \setminus \{0\}$. We assume that x and y are linearly independent and that $\delta_C(x,y) < \infty$. Define $a = \inf |E(x,y)| > 0$ and $b = \sup |E(x,y)| < \infty$. We consider a disk D(c,r) of center c and radius r > 0 included in E(x,y). Since each $z \in \overline{D}(c,r)$

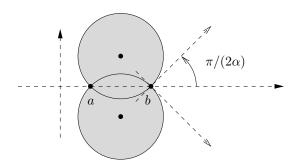


Figure 2: The complement of Ω_{α} .

must satisfy $a \leq |z| \leq b$, we have $|c| + r \leq b$ and $|c| - r \geq a$. As $0 \notin \overline{D}(c,r)$, we have for all $z \in \overline{D}(c,r)$,

$$\left|\arg\frac{z}{c}\right| \le \arcsin\frac{r}{|c|} \le \theta_{\max} := \arcsin\frac{b-a}{b+a} \in (0, \frac{\pi}{2}).$$
 (5.37)

Let $z_1, z_2 \in E(x, y)$. There exist $(m_1, l_1), (m_2, l_2) \in \mathcal{F}(x, y)$ such that $z_k \in D_{m_k, l_k}$. Since, $\delta_C(x, y) < \infty$, each $D_{m,l}, (m, l) \in \mathcal{F}(x, y)$ is an open finite disk, whose closure passes through the two distinct points: $\langle l, y \rangle / \langle l, x \rangle$ and $\langle m, y \rangle / \langle m, x \rangle$. Since $(m_1, l_1), (m_2, l_2) \in \mathcal{F}(x, y)$, one may find a couple, say (m_1, m_2) , such that $\langle m_1, y \rangle / \langle m_1, x \rangle$ and $\langle m_2, y \rangle / \langle m_2, x \rangle$ are distinct, hence $(m_1, m_2) \in \mathcal{F}(x, y)$. Thus, the disk \overline{D}_{l_1, m_1} intersects \overline{D}_{m_1, m_2} which in turn intersects \overline{D}_{m_2, l_2} . Since they are all included in $\overline{E}(x, y)$, we may use inequality (5.37). We deduce that the argument of $z \in E(x, y)$ varies within an angle $\leq 6 \, \theta_{\text{max}}$ provided b/a is sufficiently close to 1 (in order to have $6 \, \theta_{\text{max}} < \pi/2$). Up to a rotation, (or equivalently, after replacing y by λy , $\lambda \in \mathbb{C}$, $|\lambda| = 1$), we may assume that E(x, y) is included in the set

$$S(b/a) := \{z : \arg(z) \in [-3\theta_{\max}, 3\theta_{\max}], \text{ and } |z| \in [a, b]\}.$$

Next, we show that for b/a sufficiently close to 1 and for a suitable choice of α (not depending on b/a) the set S(b/a) is contained in $\hat{\mathbb{C}} \setminus \Omega_{\alpha}$. Let $r \in [a, b]$ and $\theta \in [0, 3\theta_{\max}]$. Then $re^{i\theta} \in \hat{\mathbb{C}} \setminus \Omega_{\alpha}$ iff

$$\left| re^{i\theta} - \left(\frac{a+b}{2} + i \frac{b-a}{2\tan(\pi/(2\alpha))} \right) \right| \le \frac{b-a}{2\sin(\pi/(2\alpha))}.$$

We need only to check this inequality for r = a, r = b. In those cases, the preceding inequality is equivalent to

$$1 \le \cos \theta + \frac{\sin \theta}{\tan(\pi/(2\alpha))} \frac{b-a}{b+a} \iff 2 \arctan \frac{b-a}{(b+a)\tan(\pi/(2\alpha))} \ge \theta.$$

Therefore, S(b/a) is included in $\hat{\mathbb{C}} \setminus \Omega_{\alpha}$ if and only if

$$\left(\tan\frac{\pi}{2\alpha}\right)^{-1} \ge \frac{\tan(\frac{3}{2}\arcsin\sigma)}{\sigma}, \quad \sigma = \frac{b/a - 1}{b/a + 1} \in (0, 1). \tag{5.38}$$

The RHS of (5.38) tends to 3/2 as $\sigma \to 0$. So, if we take $\alpha > \pi/(2\arctan(2/3)) \approx 2.67$, we may find $\delta_0 > 0$ such that as soon as $\log(b/a) = \delta_C(x,y) \leq \delta_0$, inequality (5.38) holds. Then $\Omega_{\alpha} \subset \mathring{L}(x,y)$ and the lemma follows from (5.36).

Proposition 5.5. We have for all $x, y \in C$, $d_C(x, y) \le \pi \sqrt{2} \exp(\delta_C(x, y)/2)$.

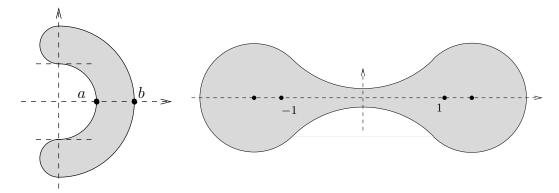


Figure 3: Region A.

Figure 4: Region Ω .

Proof. We may assume that $\delta_C(x,y) < \infty$ and that x and y are linearly independent. Denote $a = \inf |E(x,y)| > 0$, and $b = \sup |E(x,y)| < \infty$. Since $b < \infty$, all $D_{m,l}$, $(m,l) \in \mathcal{F}(x,y)$, are open finite disks. By Lemma 4.3, the closed convex hull of the centers is included in $\overline{E(x,y)}$. So this convex set does not intersect the open disk D(0,a) of radius a centered at 0. It may therefore be separated from D(0,a) by an affine (real) line. Up to a rotation (or equivalently, up to replacing y by αy , $\alpha \in \mathbb{C}$, $|\alpha| = 1$), we may assume that this line has equation $\Re(z) = a$. Now, let D(c,r) be a disk included in E(x,y) whose center c satisfies $\Re(c) \geq a$. Since the disk D(c,r) must also be included in the closed annulus $\{z: a \leq |z| \leq b\}$, we see that D(c,r) is included in the closed region A bounded by the right half circles of center 0 and radius a and a, the left half circle of center a and radius a and radiu

We consider now the Möbius transformation

$$h(z) = \frac{z + \sqrt{ab}}{z - \sqrt{ab}}. (5.39)$$

We will denote $\tau = b/a > 1$. Then we have the following (where D(c, r) denotes the open disk of center c and radius r):

-
$$h$$
 maps $D(0, a)$ onto $D\left(-\frac{\tau+1}{\tau-1}, \frac{2\sqrt{\tau}}{\tau-1}\right)$.

-
$$h \text{ maps } \hat{\mathbb{C}} \setminus \overline{D}(0,b) \text{ onto } D\left(+\frac{\tau+1}{\tau-1},\frac{2\sqrt{\tau}}{\tau-1}\right).$$

-
$$h \text{ maps } \overline{D}\left(+i\frac{b+a}{2}, \frac{b-a}{2}\right) \text{ onto } \overline{D}\left(-i\frac{\tau+1}{2\sqrt{\tau}}, \frac{\tau-1}{2\sqrt{\tau}}\right).$$

-
$$h \text{ maps } \overline{D}\left(-i\frac{b+a}{2}, \frac{b-a}{2}\right) \text{ onto } \overline{D}\left(+i\frac{\tau+1}{2\sqrt{\tau}}, \frac{\tau-1}{2\sqrt{\tau}}\right).$$

- h maps respectively $0, \infty$ to -1, 1, and the left half-plane to the unit disk.

Thus $\hat{\mathbb{C}} \setminus A$ is mapped by h onto an open set $\Omega \subset \mathbb{C}$ as in figure 4. If $t \in [-1, 1]$, then the distance $\rho(t)$ from t to the boundary of Ω is given by

$$\rho(t) = \left| t + i \frac{\tau + 1}{2\sqrt{\tau}} \right| - \frac{\tau - 1}{2\sqrt{\tau}} = \sqrt{t^2 + \frac{(\tau + 1)^2}{4\tau}} - \frac{\tau - 1}{2\sqrt{\tau}}.$$

If p(z)|dz| denotes the Poincaré metric on Ω , then $p(z) \leq 2/\rho(z)$ (see e.g. [Mil06], p223). Therefore,

$$d_{C}(x,y) \leq d_{\hat{\mathbb{C}}\backslash A}(0,\infty) = d_{\Omega}(-1,1)$$

$$\leq \int_{-1}^{1} \frac{2dt}{\rho(t)} = 2 \int_{-1}^{1} \frac{\sqrt{t^{2} + \frac{(\tau+1)^{2}}{4\tau}} + \frac{\tau-1}{2\sqrt{\tau}}}{t^{2} + 1} dt$$

$$\leq 2 \int_{-1}^{1} \frac{\sqrt{2} \frac{\tau+1}{2\sqrt{\tau}} + \frac{\tau-1}{2\sqrt{\tau}}}{t^{2} + 1} dt \leq \pi \sqrt{2\tau}$$

$$= \pi \sqrt{2} \exp(\delta_{C}(x,y)/2)$$
(5.40)

Hence the result.

Remark 6. One cannot find a simpler bound in Proposition 5.5. Indeed, let consider the following sequences of elements of \mathbb{C}^3_+ :

$$x_k = \left(1, e^{i(\pi/2 - \pi/(2k))}, e^{i(\pi/2 - \pi/(2k))}\right),$$

$$y_k = \left(2, e^{i(\pi/2 - \pi/(2k))}, e^{i(\pi/2 - \pi/(2k))} + 2i\cos\frac{\pi}{2k}\right),$$

$$z_k = \left(\frac{2}{\sqrt{3}\cos\frac{\pi}{2k} + \sin\frac{\pi}{2k}}, 1, 1\right).$$

Using similar techniques, one shows that $d_{\mathbb{C}^3_+}(x_k, y_k) \geq k \log 2$, and that $d_{\mathbb{C}^3_+}(z_k, x_k)$ and $d_{\mathbb{C}^3_+}(z_k, y_k)$ are $O(\log k)$. Therefore, $(d_{\mathbb{C}^3_+}(x_k, z_k) + d_{\mathbb{C}^3_+}(z_k, y_k))/d_{\mathbb{C}^3_+}(x_k, y_k) \to 0$. This is because, in $E_{\mathbb{C}^3_+}(x_k, y_k)$, there are two disks intersecting making a very small angle, $\pi/(2k)$, and thus are almost tangent; whereas in $E_{\mathbb{C}^3_+}(z_k, y_k)$ and $E_{\mathbb{C}^3_+}(z_k, x_k)$ the angles do not tend to 0.

Finally, consider the 3×3 matrix $A_k = (a_{ij})$ where $a_{ii} = 1$ and $a_{ij} = \alpha/k$ for $i \neq j$, $\alpha > 0$. Theorem 3.6 shows that $\delta_{\mathbb{C}^3_+}$ -diam $A(\mathbb{C}^3_+ \setminus \{0\}) = O(\log k)$. One also checks that for $0 < \alpha < \pi/16$ and k large enough, one has $A_k^{-1}x_k$, $A_k^{-1}y_k \in \mathbb{C}^3_+$ (x_k, y_k) as above), so that $d_{\mathbb{C}^3_+}$ -diam $A(\mathbb{C}^3_+ \setminus \{0\}) \geq d_{\mathbb{C}^3_+}(x_k, y_k) \geq k \log 2$.

Theorem 5.6. Let C satisfy (C1)-(C2). Let $C_1 \subset C$ be any complex subcone of C. Consider the three diameters of C_1 with respect to δ_C , d_C , \tilde{d}_C . If any of these diameters is finite, then the two others are also finite.

Proof. This comes immediately from Propositions 5.5 and 5.2.

Theorem 5.7. Let $C_1 \subset V_1$, $C_2 \subset V_2$ satisfy (C1)-(C2). Let $T: V_1 \to V_2$ be a linear map, and suppose that $T(C_1 \setminus \{0\}) \subset C_2 \setminus \{0\}$. If the diameter $\tilde{\Delta} = \sup \tilde{d}_{C_2}(Tx, Ty)$ is finite, then we have

$$\forall x, y \in C_1, \quad \tilde{d}_{C_2}(Tx, Ty) \le \tanh\left(\frac{\pi \exp(\tilde{\Delta})}{2\sqrt{2}}\right) \tilde{d}_{C_1}(x, y).$$

Proof. Denote by Δ the diameter of $T(C_1 \setminus \{0\})$ with respect to d_C . Then from Propositions 5.5 and 5.3, we have $\Delta \leq \pi \sqrt{2} \exp(\tilde{\Delta})$. The conclusion then follows from Theorem 5.1 and the definition of \tilde{d}_C .

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